

IMPERIAL COLLEGE LONDON
UNIVERSITY OF LONDON
BSc and MSci EXAMINATIONS (MATHEMATICS)
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M3S8 (Solutions)

Time Series

Setter's signature	Checker's signature	Editor's signature
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1. (a)

seen ↓

$$\begin{aligned}\mathbb{E}(X_t^2) &= \mathbb{E}(\sigma_t^2 \varepsilon_t^2) \\ &= \mathbb{E}((a_0 + a_1 X_{t-1}^2) \varepsilon_t^2) \\ &= (a_0 + a_1 \mathbb{E}(X_{t-1}^2)) \mathbb{E}(\varepsilon_t^2) \\ &= a_0 + a_1 \mathbb{E}(X_t^2),\end{aligned}$$

which yields

$$\mathbb{E}(X_t^2) = \frac{a_0}{1 - a_1}.$$

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(b)

method seen ↓

$$\begin{aligned}X_t^4 &= (a_0 + a_1 X_{t-1}^2)^2 \varepsilon_t^4 \\ &= (a_0^2 + 2a_0 a_1 X_{t-1}^2 + a_1^2 X_{t-1}^4) \varepsilon_t^4.\end{aligned}$$

Hence,

$$\mathbb{E}(X_t^4) = 3 \left(a_0^2 + 2a_0 a_1 \frac{a_0}{1 - a_1} + a_1^2 \mathbb{E}(X_t^4) \right),$$

which gives

$$\mathbb{E}(X_t^4) = \frac{3a_0^2(1 + a_1)}{(1 - a_1)(1 - 3a_1^2)}.$$

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(c)

unseen ↓

$$\kappa_{X_t} = \frac{\mathbb{E}(X_t^4)}{(\mathbb{E}(X_t^2))^2} = \frac{3a_0^2(1 + a_1)}{(1 - a_1)(1 - 3a_1^2)} \frac{(1 - a_1)^2}{a_0^2} = \frac{3(1 - a_1^2)}{1 - 3a_1^2}.$$

Note that $\kappa_{X_t} > 3$ as $1 - a_1^2 > 1 - 3a_1^2$ for $a_1 > 0$. On the other hand, if $Z \sim N(0, \sigma^2)$, then

$$\kappa_Z = \frac{\mathbb{E}(Z^4)}{(\mathbb{E}(Z^2))^2} = \frac{3\sigma^4}{(\sigma^2)^2} = 3.$$

Therefore, X_t is not Normally distributed.

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(d)

method seen ↓

$$\rho_1 = \frac{\mathbb{E}(X_t^2 X_{t-1}^2) - (\mathbb{E}(X_t^2))^2}{\mathbb{E}(X_t^4) - (\mathbb{E}(X_t^2))^2} =: \frac{A - B^2}{C - B^2}.$$

We have already computed B and C . It remains to compute A .

$$\begin{aligned}\mathbb{E}(X_t^2 X_{t-1}^2) &= \mathbb{E}(\varepsilon_t^2 (a_0 \mathbb{E}(X_{t-1}^2) + a_1 \mathbb{E}(X_{t-1}^4))) \\ &= a_0 \frac{a_0}{1 - a_1} + a_1 \frac{3a_0^2(1 + a_1)}{(1 - a_1)(1 - 3a_1^2)} \\ &= \frac{a_0^2(1 + 3a_1)}{(1 - a_1)(1 - 3a_1^2)}.\end{aligned}$$

Substituting into the above, we obtain $\rho_1 = a_1$.

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2. (a) We have

method seen ↓

$$\begin{bmatrix} \hat{s}_1 \\ \hat{s}_2 \end{bmatrix} = \begin{bmatrix} \hat{s}_0 & \hat{s}_1 \\ \hat{s}_1 & \hat{s}_0 \end{bmatrix} \begin{bmatrix} \hat{a}^{YW} \\ \hat{b}^{YW} \end{bmatrix},$$

which gives

$$\begin{bmatrix} \hat{a}^{YW} \\ \hat{b}^{YW} \end{bmatrix} = \frac{1}{\hat{s}_0^2 - \hat{s}_1^2} \begin{bmatrix} \hat{s}_0 & -\hat{s}_1 \\ -\hat{s}_1 & \hat{s}_0 \end{bmatrix} \begin{bmatrix} \hat{s}_1 \\ \hat{s}_2 \end{bmatrix} = \begin{bmatrix} \frac{\hat{s}_0 \hat{s}_1 - \hat{s}_1 \hat{s}_2}{\hat{s}_0^2 - \hat{s}_1^2} \\ \frac{\hat{s}_0 \hat{s}_2 - \hat{s}_1^2}{\hat{s}_0^2 - \hat{s}_1^2} \end{bmatrix}.$$

Substituting

$$\hat{s}_\tau = \frac{1}{n} \sum_{t=1}^{n-|\tau|} x_t x_{t+|\tau|},$$

we obtain

$$\begin{aligned} \hat{a}^{YW} &= \frac{\sum_{t=1}^{n-1} x_t x_{t+1} \left(\sum_{t=1}^n x_t^2 - \sum_{t=1}^{n-2} x_t x_{t+2} \right)}{\left(\sum_{t=1}^n x_t^2 \right)^2 - \left(\sum_{t=1}^{n-1} x_t x_{t+1} \right)^2} \\ \hat{b}^{YW} &= \frac{\sum_{t=1}^n x_t^2 \sum_{t=1}^{n-2} x_t x_{t+2} - \left(\sum_{t=1}^{n-1} x_t x_{t+1} \right)^2}{\left(\sum_{t=1}^n x_t^2 \right)^2 - \left(\sum_{t=1}^{n-1} x_t x_{t+1} \right)^2} \end{aligned}$$

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(b) We have

method seen ↓

$$\begin{bmatrix} \hat{a}^{LS} \\ \hat{b}^{LS} \end{bmatrix} = (F^T F)^{-1} F^T \mathbf{x}_{(2)},$$

where

$$\begin{aligned} F^T &= \begin{bmatrix} x_2 & \cdots & x_{n-1} \\ x_1 & \cdots & x_{n-2} \end{bmatrix} \\ \mathbf{x}_{(2)}^T &= (x_3, \dots, x_n). \end{aligned}$$

Thus,

$$\begin{aligned} \begin{bmatrix} \hat{a}^{LS} \\ \hat{b}^{LS} \end{bmatrix} &= \begin{bmatrix} \sum_{t=2}^{n-1} x_t^2 & \sum_{t=1}^{n-2} x_t x_{t+1} \\ \sum_{t=1}^{n-2} x_t x_{t+1} & \sum_{t=1}^{n-2} x_t^2 \end{bmatrix}^{-1} \begin{bmatrix} \sum_{t=2}^{n-1} x_t x_{t+1} \\ \sum_{t=1}^{n-2} x_t x_{t+2} \end{bmatrix} \\ &= \frac{1}{\sum_{t=2}^{n-1} x_t^2 \sum_{t=1}^{n-2} x_t^2 - \left(\sum_{t=1}^{n-2} x_t x_{t+1} \right)^2} \\ &\quad \times \begin{bmatrix} \sum_{t=1}^{n-2} x_t^2 & -\sum_{t=1}^{n-2} x_t x_{t+1} \\ -\sum_{t=1}^{n-2} x_t x_{t+1} & \sum_{t=2}^{n-1} x_t^2 \end{bmatrix} \begin{bmatrix} \sum_{t=2}^{n-1} x_t x_{t+1} \\ \sum_{t=1}^{n-2} x_t x_{t+2} \end{bmatrix}. \end{aligned}$$

This leads to

$$\begin{aligned} \hat{a}^{LS} &= \frac{\sum_{t=1}^{n-2} x_t^2 \sum_{t=2}^{n-1} x_t x_{t+1} - \sum_{t=1}^{n-2} x_t x_{t+1} \sum_{t=1}^{n-2} x_t x_{t+2}}{\sum_{t=2}^{n-1} x_t^2 \sum_{t=1}^{n-2} x_t^2 - \left(\sum_{t=1}^{n-2} x_t x_{t+1} \right)^2} \\ \hat{b}^{LS} &= \frac{\sum_{t=2}^{n-1} x_t^2 \sum_{t=1}^{n-2} x_t x_{t+2} - \sum_{t=1}^{n-2} x_t x_{t+1} \sum_{t=2}^{n-1} x_t x_{t+1}}{\sum_{t=2}^{n-1} x_t^2 \sum_{t=1}^{n-2} x_t^2 - \left(\sum_{t=1}^{n-2} x_t x_{t+1} \right)^2}. \end{aligned}$$

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(c) (i) For $n = 3$, $\hat{a}^{LS}$ does not make sense as we have $\hat{a}^{LS} = 0/0$, so Yule-Walker should be used.

unseen ↓

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(ii) As n tends to infinity, from the above formulae it is apparent that the corresponding Yule-Walker and least squares estimates become “closer and closer” to each other. Therefore, it “does not matter” which one is used in the case $n = 10^{10}$ as the estimated values will probably be very similar for both methods.

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3. (a) For $\tau > 0$,

unseen ↓

$$\mathbb{E}(X_t X_{t-\tau}) = \mathbb{E}(a_t) \mathbb{E}(X_{t-1} X_{t-\tau}) + \sqrt{8/9} \mathbb{E}(\varepsilon_t) \mathbb{E}(X_{t-\tau}),$$

which, from the properties of the Uniform distribution, gives

$$s_\tau = \frac{1}{2} s_{\tau-1}.$$

Also,

$$s_0 = \mathbb{E}(X_t^2) = \mathbb{E}(a_t^2 X_{t-1}^2 + 2\sqrt{8/9} a_t X_{t-1} \varepsilon_t + 8/9 \varepsilon_t^2) = 1/3 \mathbb{E}(X_t^2) + 8/9,$$

which yields $s_0 = 4/3$. Thus,

$$s_\tau = \frac{4}{3} \left(\frac{1}{2}\right)^{|\tau|}.$$

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(b) To compute the autocovariance function $\tilde{s}_\tau$ of Y_t , we use exactly the same technique as in (a) above and find that

seen ↓

$$\tilde{s}_\tau = \frac{4}{3} \left(\frac{1}{2}\right)^{|\tau|} = s_\tau.$$

Thus, the autocovariance functions are the same.

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(c) The autocovariance function of X_t is the same as that of Y_t (see above). Therefore, the spectral densities will also be the same (as the spectral density is the Fourier transform of the autocovariance sequence). Denoting the spectral density of a process Z_t by $S_Z(f)$, we have

seen ↓

$$|1 - 1/2 \exp(-i2\pi f)|^2 S_X(f) = S_\varepsilon(f),$$

which simplifies to

$$(5/4 - \cos(2\pi f)) S_X(f) = 1,$$

and therefore

$$S_X(f) = (5/4 - \cos(2\pi f))^{-1}.$$

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(d) The distributions are not identical. To see this, it is enough to show, for example, that $\mathbb{E}(X_t^4) \neq \mathbb{E}(Y_t^4)$. We compute

unseen ↓

$$\begin{aligned} \mathbb{E}(X_t^4) &= \mathbb{E}\left(a_t^4 X_{t-1}^4 + 4a_t^3 X_{t-1}^3 \sqrt{8/9} \varepsilon_t + 6a_t^2 X_{t-1}^2 8/9 \varepsilon_t^2 + 4a_t X_{t-1} (8/9)^{3/2} \varepsilon_t^3 + (8/9)^2 \varepsilon_t^4\right) \\ &= 1/5 \mathbb{E}(X_t^4) + 6 \cdot 1/3 \cdot 4/3 \cdot 8/9 + 3(8/9)^2, \end{aligned}$$

which gives $\mathbb{E}(X_t^4) = 160/27$. On the other hand,

$$\begin{aligned} \mathbb{E}(Y_t^4) &= \mathbb{E}\left(1/16 Y_{t-1}^4 + 4/8 Y_{t-1}^3 \varepsilon_t + 6/4 Y_{t-1}^2 \varepsilon_t^2 + 4/2 Y_{t-1} \varepsilon_t^3 + \varepsilon_t^4\right) \\ &= 1/16 \mathbb{E}(Y_t^4) + 6/4 \cdot 4/3 + 3, \end{aligned}$$

which gives $\mathbb{E}(Y_t^4) = 16/3 \neq 160/27$.

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4. (a)

sim. seen ↓

$$\begin{aligned}
 \text{MSE}(\hat{\mu}, \mu) &= n^{-2} \sum_{s,t=1}^n s_{t-s} \\
 &= n^{-2} (ns_0 + 2(n-1)s_1 + \dots + 2s_{n-1}) \\
 &\leq 2n^{-1} (s_0 + \dots + s_{n-1}) \\
 &= 2s_0n^{-1} + 2n^{-1} \sum_{\tau=1}^{n-1} \frac{1}{\tau} \left(1 + \dots + \frac{1}{\tau}\right) \\
 &= 2s_0n^{-1} + 2n^{-1} \sum_{\tau=1}^{n-1} \frac{1}{\tau} O(\log(\tau)) \\
 &\leq 2s_0n^{-1} + 2O(\log(n))n^{-1} \sum_{\tau=1}^{n-1} \frac{1}{\tau} \\
 &= 2s_0n^{-1} + 2O(\log^2(n))n^{-1} \\
 &\rightarrow 0 \quad \text{as } n \rightarrow \infty.
 \end{aligned}$$

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(b)

unseen ↓

$$\begin{aligned}
 0 &= n \left(\frac{1}{n} \sum_{s=1}^n (x_s - \hat{\mu}) \right)^2 \\
 &= \frac{1}{n} \sum_{s=1}^n \sum_{t=1}^n (x_s - \hat{\mu})(x_t - \hat{\mu}) \\
 &= \frac{1}{n} \sum_{|\tau| < n} \sum_{t=1}^{n-|\tau|} (x_t - \hat{\mu})(x_{t+|\tau|} - \hat{\mu}).
 \end{aligned}$$

5

(c) Recall the spectral representation theorem

seen ↓

$$X_t = \int_{-1/2}^{1/2} e^{i2\pi f't} dZ(f').$$

We have $\mathbb{E}(\hat{S}(f)) = \mathbb{E}|J(f)|^2$, where

$$\begin{aligned}
 J(f) &= \frac{1}{\sqrt{n}} \sum_{t=1}^n X_t e^{-i2\pi ft} \\
 &= \sum_{t=1}^n \left(\int_{-1/2}^{1/2} \frac{1}{\sqrt{n}} e^{i2\pi f't} dZ(f') \right) e^{-i2\pi ft} \\
 &= \int_{-1/2}^{1/2} \sum_{t=1}^n \frac{1}{\sqrt{n}} e^{-i2\pi(f-f')t} dZ(f')
 \end{aligned}$$

We find that,

$$\begin{aligned}
 \mathbb{E}\{\widehat{S}(f)\} &= \mathbb{E}\{|J(f)|^2\} = \mathbb{E}\{J^*(f)J(f)\} \\
 &= \mathbb{E}\left\{\int_{-1/2}^{1/2} \sum_{t=1}^n \frac{1}{\sqrt{n}} e^{i2\pi(f-f')t} dZ^*(f') \int_{-1/2}^{1/2} \sum_{s=1}^n \frac{1}{\sqrt{n}} e^{-i2\pi(f-f'')s} dZ(f'')\right\} \\
 &= \int_{-1/2}^{1/2} \int_{-1/2}^{1/2} \sum_{t=1}^n \frac{1}{\sqrt{n}} e^{i2\pi(f-f')t} \sum_{s=1}^n \frac{1}{\sqrt{n}} e^{-i2\pi(f-f'')s} \mathbb{E}\{dZ^*(f') dZ(f'')\} \\
 &= \int_{-1/2}^{1/2} \mathcal{F}(f-f') S(f') df',
 \end{aligned}$$

where

$$\mathcal{F}(f) = \left| \sum_{t=1}^n \frac{1}{\sqrt{n}} e^{-i2\pi ft} \right|^2.$$

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(d) Define the process

$$X_t = \sum_{k=1}^{\infty} \frac{1}{k} \varepsilon_{t-k+1}.$$

sim. seen ↓

We have

$$s_0 = \text{Var}(X_t) = \sum_{k=1}^{\infty} k^{-2} = \pi^2/6,$$

and for $\tau \geq 1$,

$$\begin{aligned}
 s_{\tau} &= \mathbb{E}\left(\sum_{k=1}^{\infty} \frac{1}{k} \varepsilon_{t-k+1} \sum_{l=1}^{\infty} \frac{1}{l} \varepsilon_{t+\tau-l+1}\right) \\
 &= \sum_{k=1}^{\infty} \frac{1}{k(k+\tau)} \\
 &= \sum_{k=1}^{\infty} \frac{1}{\tau} \left(\frac{1}{k} - \frac{1}{k+\tau}\right) \\
 &= \frac{1}{\tau} \left(1 + \frac{1}{2} + \dots + \frac{1}{\tau}\right).
 \end{aligned}$$

So s_{τ} is a valid autocovariance function.

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5. (a) We want to minimize,

seen ↓

$$\begin{aligned} E\{(X_{t+l} - X_t(l))^2\} &= E\left\{\left(\sum_{k=0}^{\infty} \psi_k \varepsilon_{t+l-k} - \sum_{k=0}^{\infty} \delta_k \varepsilon_{t-k}\right)^2\right\} \\ &= E\left\{\left(\sum_{k=0}^{l-1} \psi_k \varepsilon_{t+l-k} + \sum_{k=0}^{\infty} [\psi_{k+l} - \delta_k] \varepsilon_{t-k}\right)^2\right\} \\ &= \sigma_{\varepsilon}^2 \left\{ \left(\sum_{k=0}^{l-1} \psi_k^2\right) + \sum_{k=0}^{\infty} (\psi_{k+l} - \delta_k)^2 \right\}. \end{aligned}$$

The first term is independent of the choice of the $\{\delta_k\}$ and the second term is clearly minimized by choosing $\delta_k = \psi_{k+l}, k = 0, 1, 2, \dots$

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(b) We have $X_t = \Psi(B)\varepsilon_t \Rightarrow \varepsilon_t = \Psi^{-1}(B)X_t$, and so

method seen ↓

$$\begin{aligned} X_t(l) &= \sum_{k=0}^{\infty} \psi_{k+l} \varepsilon_{t-k} = \Psi^{(l)}(B)\varepsilon_t \quad [= \delta(B)\varepsilon_t] \\ &= \Psi^{(l)}(B)\Psi^{-1}(B)X_t = G^{(l)}(B)X_t \end{aligned}$$

Now

$$X_t - aX_{t-1} = \varepsilon_t \Rightarrow (1 - aB)X_t = \varepsilon_t$$

So that,

$$\Rightarrow \Psi(B) = (1 - aB)^{-1} = 1 + aB + a^2B^2 + \dots$$

So $\delta_k = \psi_{k+l} = a^{k+l}$ and when $l = 1$, $\delta_k = a^{k+1}$ giving

$$\Psi^{(1)}(B) = (a + a^2B + a^3B^2 + \dots)$$

We have,

$$G^{(1)}(B) = \Psi^{(1)}(B)\Psi^{-1}(B) = (a + a^2B + a^3B^2 + \dots)(1 - aB) = a.$$

Giving

$$X_t(1) = G^{(1)}(B)X_t = aX_t$$

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(c) Recalling that $s_{\tau} = a^{|\tau|}/(1 - a^2)$, it is easily seen that

unseen ↓

$$\Gamma_{(n)}\mathbf{a} = \gamma_{(n)}.$$

The result follows upon applying $\Gamma_{(n)}^{-1}$ to both sides of the above equation.

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