## **EE2** Mathematics

## The role of grad, div and curl in vector calculus

The gradient operator  $\nabla$  is defined as

$$abla = \hat{oldsymbol{i}} \, rac{\partial}{\partial x} + \hat{oldsymbol{j}} \, rac{\partial}{\partial y} + \hat{oldsymbol{k}} \, rac{\partial}{\partial z}$$

Using this operator on a scalar field  $\phi = \phi(x, y, z)$  gives the gradient of  $\phi$ 

$$ext{grad}\,\phi = 
abla \phi = \hat{oldsymbol{i}}\, rac{\partial \phi}{\partial x} + \hat{oldsymbol{j}}\, rac{\partial \phi}{\partial y} + \hat{oldsymbol{k}}\, rac{\partial \phi}{\partial z}$$

Note that  $\nabla \phi$  is a vector. Since  $\nabla$  is a *vector* operator it can act upon a vector field

$$A(x, y, z) = i A_1(x, y, z) + j A_2(x, y, z) + k A_3(x, y, z)$$

through the dot product. This defines the *divergence* of a vector (which is itself a scalar)

div 
$$\boldsymbol{A} = \nabla \cdot \boldsymbol{A} = \frac{\partial A_1}{\partial x} + \frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z}$$

which physically expresses how the vector  $\mathbf{A}$  changes spatially through the six faces of a 3D-box<sup>1</sup>. Note, however, that  $\nabla \cdot \mathbf{A} \neq \mathbf{A} \cdot \nabla$ : the RHS is a differential operator while the LHS is a scalar function.

The *curl* of a vector (which is itself a vector) is defined by

$$\operatorname{curl} oldsymbol{A} = 
abla imes oldsymbol{A} = \left| egin{array}{cc} \hat{oldsymbol{i}} & \hat{oldsymbol{j}} & \hat{oldsymbol{j}} & \hat{oldsymbol{k}} \ rac{\partial}{\partial x} & rac{\partial}{\partial y} & rac{\partial}{\partial z} \ A_1 & A_2 & A_3 \end{array} 
ight|.$$

This expresses how much swirl is in a vector field; if  $\mathbf{r}$  is the line from the origin to the point (x, y, z) then curl  $\mathbf{r} = 0$ .

There are various identities that are useful:

1. The gradient of the product of two scalars  $\phi$  and  $\psi$ 

$$\nabla(\phi\psi) = \psi\nabla\phi + \phi\nabla\psi$$

2. The divergence of the product of a scalar  $\phi$  with a vector  $\boldsymbol{A}$ 

$$\operatorname{div}(\phi \boldsymbol{A}) = \phi \operatorname{div} \boldsymbol{A} + (\nabla \phi) \cdot \boldsymbol{A}$$

3. The curl of the product of a scalar  $\phi$  with a vector  $\boldsymbol{A}$ 

$$\operatorname{curl}(\phi \boldsymbol{A}) = \phi \operatorname{curl} \boldsymbol{A} + (\nabla \phi) \times \boldsymbol{A}$$

4. The curl of the gradient of any scalar  $\phi$ 

$$\operatorname{curl}\left(\nabla\phi\right) = \nabla \times \nabla\phi = 0.$$

5. The divergence of the curl of any vector  $\boldsymbol{A}$ 

$$\operatorname{div}\left(\operatorname{curl} \boldsymbol{A}\right) = \nabla \cdot \left(\nabla \times \boldsymbol{A}\right) = 0$$

The cyclic rule for the scalar triple product shows that this is zero for all vectors A because two vectors in the triple  $(\nabla)$  are the same.

<sup>&</sup>lt;sup>1</sup>One can think of a vector field that has zero divergence as 'incompressible'.