## Civ.Eng. 2 Mathematics: Grad, Div and Curl

This sheet can be found on the Web: http://www.ma.ic.ac.uk/~ajm8/Civ2

A function  $\underline{\mathbf{F}}$  which associates a vector value  $\underline{\mathbf{F}}(\underline{\mathbf{r}}) \equiv \underline{\mathbf{F}}(x,y,z) \equiv F_1(\underline{\mathbf{r}})\underline{\mathbf{i}} + F_2(\underline{\mathbf{r}})\underline{\mathbf{j}} + F_3(\underline{\mathbf{r}})\underline{\mathbf{k}}$  with every position vector  $\underline{\mathbf{r}} \equiv x \, \underline{\mathbf{i}} + y \, \underline{\mathbf{j}} + z \, \underline{\mathbf{k}}$  is said to be a **VECTOR FIELD**, e.g. velocity of a fluid.

Recall if  $f(\mathbf{r})$  is a scalar field, then

the gradient of 
$$f \equiv \operatorname{grad} f \equiv \nabla f \equiv \frac{\partial f}{\partial x} \underline{\mathbf{i}} + \frac{\partial f}{\partial y} \underline{\mathbf{j}} + \frac{\partial f}{\partial z} \underline{\mathbf{k}}$$
. (1)

$$\nabla \equiv \underline{\mathbf{i}} \frac{\partial}{\partial x} + \underline{\mathbf{j}} \frac{\partial}{\partial y} + \underline{\mathbf{k}} \frac{\partial}{\partial z}$$
 is a **VECTOR OPERATOR**,  $\nabla$ : scalar field  $\rightarrow$  vector field.

Now introduce

the divergence of 
$$\underline{\mathbf{F}} \equiv \operatorname{div} \underline{\mathbf{F}} \equiv \nabla \cdot \underline{\mathbf{F}} \equiv \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z}$$
. (2)

Note that

$$\nabla \cdot \mathbf{F} \not\equiv \mathbf{F} \cdot \nabla \equiv F_1 \frac{\partial}{\partial x} + F_2 \frac{\partial}{\partial y} + F_3 \frac{\partial}{\partial z} \,,$$

which is the scalar operator we met before when finding directional derivatives; i.e.

$$\underline{\mathbf{F}} \cdot (\nabla f) \equiv F_1 \frac{\partial f}{\partial x} + F_2 \frac{\partial f}{\partial y} + F_3 \frac{\partial f}{\partial z} \equiv (\underline{\mathbf{F}} \cdot \nabla) f.$$

Similarly, we introduce

$$\operatorname{curl} \mathbf{\underline{F}} \equiv \nabla \times \mathbf{\underline{F}} \equiv \begin{vmatrix} \mathbf{\underline{i}} & \mathbf{\underline{j}} & \mathbf{\underline{k}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix}$$

$$\equiv \left( \frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) \mathbf{\underline{i}} - \left( \frac{\partial F_3}{\partial x} - \frac{\partial F_1}{\partial z} \right) \mathbf{\underline{j}} + \left( \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) \mathbf{\underline{k}}. \tag{3}$$

The equivalent notation curl  $\underline{\mathbf{F}} \equiv \nabla \wedge \underline{\mathbf{F}}$  is sometimes used.

Note that  $\nabla \times \underline{\mathbf{F}} \not\equiv \underline{\mathbf{F}} \times \nabla$ , which is a vector operator; i.e.

$$\underline{\mathbf{F}} \times (\nabla f) \equiv \left( F_2 \frac{\partial f}{\partial z} - F_3 \frac{\partial f}{\partial y} \right) \underline{\mathbf{i}} - \left( F_1 \frac{\partial f}{\partial z} - F_3 \frac{\partial f}{\partial x} \right) \underline{\mathbf{j}} + \left( F_1 \frac{\partial f}{\partial y} - F_2 \frac{\partial f}{\partial x} \right) \underline{\mathbf{k}}$$
$$\equiv (\underline{\mathbf{F}} \times \nabla) f.$$

Therefore we have that

**RULES:** For arbitrary scalar fields  $f(\underline{\mathbf{r}})$ ,  $g(\underline{\mathbf{r}})$  and vector fields  $\underline{\mathbf{F}}(\underline{\mathbf{r}})$ ,  $\underline{\mathbf{G}}(\underline{\mathbf{r}})$ ; then we have that

- (1)  $\Longrightarrow \nabla(f+g) \equiv (\nabla f) + (\nabla g)$ .
- (2)  $\implies \nabla \cdot (\underline{\mathbf{F}} + \underline{\mathbf{G}}) \equiv (\nabla \cdot \underline{\mathbf{F}}) + (\nabla \cdot \underline{\mathbf{G}}).$
- (3)  $\Longrightarrow \nabla \times (\underline{\mathbf{F}} + \underline{\mathbf{G}}) \equiv (\nabla \times \underline{\mathbf{F}}) + (\nabla \times \underline{\mathbf{G}})$
- (2) and  $(1) \implies$

$$\nabla \cdot (f \mathbf{\underline{F}}) \equiv \nabla \cdot \left[ (f F_1) \mathbf{\underline{i}} + (f F_2) \mathbf{\underline{j}} + (f F_3) \mathbf{\underline{k}} \right] \equiv \frac{\partial (f F_1)}{\partial x} + \frac{\partial (f F_2)}{\partial y} + \frac{\partial (f F_3)}{\partial z}$$

$$\equiv \left[ F_1 \frac{\partial f}{\partial x} + f \frac{\partial F_1}{\partial x} \right] + \left[ F_2 \frac{\partial f}{\partial y} + f \frac{\partial F_2}{\partial y} \right] + \left[ F_3 \frac{\partial f}{\partial z} + f \frac{\partial F_3}{\partial z} \right]$$

$$\equiv (\nabla f) \cdot \mathbf{\underline{F}} + f (\nabla \cdot \mathbf{\underline{F}}).$$

Similarly (3) and (1)  $\Longrightarrow$ 

$$\nabla \times (f \mathbf{F}) \equiv (\nabla f) \times \mathbf{F} + f (\nabla \times \mathbf{F}).$$

We introduce the **LAPLACIAN** operator  $\nabla^2$ : scalar field  $\rightarrow$  scalar field, defined by

$$\nabla^2 f \equiv \nabla \cdot (\nabla f) \equiv \nabla \cdot \left( \frac{\partial f}{\partial x} \mathbf{i} + \frac{\partial f}{\partial y} \mathbf{j} + \frac{\partial f}{\partial z} \mathbf{k} \right) \equiv \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}.$$

It is simple matter to show using the definitions (1), (2) and (3) that

$$\nabla \times (\nabla f) = \underline{0}$$
 and  $\nabla \cdot (\nabla \times \underline{\mathbf{F}}) = 0$ .

## RECALL: Conservative Vector Fields and Path Independence

Given a vector field  $\underline{\mathbf{F}}(\underline{\mathbf{r}}) \equiv F_1(\underline{\mathbf{r}})\underline{\mathbf{i}} + F_2(\underline{\mathbf{r}})\underline{\mathbf{j}} + F_3(\underline{\mathbf{r}})\underline{\mathbf{k}}$ , if there exists a  $\phi(\underline{\mathbf{r}})$  satisfying

$$\frac{\partial \phi}{\partial x} = F_1, \qquad \frac{\partial \phi}{\partial y} = F_2, \qquad \frac{\partial \phi}{\partial z} = F_3;$$
 (4a)

then

$$\int_{C_{\underline{\mathbf{A}} \to \underline{\mathbf{B}}}} \underline{\mathbf{F}} \cdot d\underline{\mathbf{r}} = \int_{C_{\underline{\mathbf{A}} \to \underline{\mathbf{B}}}} \left[ \frac{\partial \phi}{\partial x} dx + \frac{\partial \phi}{\partial y} dy + \frac{\partial \phi}{\partial z} dz \right] = \int_{C_{\underline{\mathbf{A}} \to \underline{\mathbf{B}}}} d\phi = \phi(\underline{\mathbf{B}}) - \phi(\underline{\mathbf{A}}); \tag{4b}$$

that is,  $\int_{C_{\underline{\mathbf{A}}-\underline{\mathbf{B}}}} \underline{\mathbf{F}} \cdot d\underline{\mathbf{r}}$  depends only on the start point  $\underline{\mathbf{A}}$  and the end point  $\underline{\mathbf{B}}$ , NOT on the particular path C joining  $\underline{\mathbf{A}}$  to  $\underline{\mathbf{B}}$ . We showed that a  $\phi$  satisfying (4a) exists, and hence that (4b) holds, if and only if  $\underline{\mathbf{F}}(\underline{\mathbf{r}})$  satisfies the 3 conditions

$$\frac{\partial F_1}{\partial y} = \frac{\partial F_2}{\partial x}, \qquad \frac{\partial F_1}{\partial z} = \frac{\partial F_3}{\partial x}, \qquad \frac{\partial F_2}{\partial z} = \frac{\partial F_3}{\partial y}.$$
 (5)

Such an  $\underline{\mathbf{F}}$  is called **CONSERVATIVE** with the corresponding  $\phi$  being the **POTENTIAL** of  $\underline{\mathbf{F}}$ . In terms of grad and curl,  $(5) \equiv \nabla \times \underline{\mathbf{F}} = \underline{0}$  and  $(4a) \equiv \underline{\mathbf{F}} = \nabla \phi$ . Therefore we have that

**F** conservative 
$$\iff \nabla \times \mathbf{F} = 0 \iff \mathbf{F} = \nabla \phi \text{ for some } \phi \iff (4b)$$
.