Conservative Forces and Path Independence

This sheet can be found on the Web: http://www.ma.ic.ac.uk/~ajm8/MEng26

Example 1: Find $\int_C \underline{\mathbf{F}} \cdot d\underline{\mathbf{r}}$, where $\underline{\mathbf{F}} = y^2 \underline{\mathbf{i}} + x^2 \underline{\mathbf{j}}$ and C is (a) the straight line y = x and (b) the curve $y = x^2$ from (0,0) to (1,1).

(a)
$$\Longrightarrow \int_C \underline{\mathbf{F}} \cdot d\underline{\mathbf{r}} = \int_C (y^2 dx + x^2 dy) = \int_C \left(y^2 + x^2 \frac{dy}{dx} \right) dx = \int_0^1 (x^2 + x^2) dx = \frac{2}{3}.$$
 (1a)

(b)
$$\Longrightarrow \int_C \underline{\mathbf{F}} \cdot d\underline{\mathbf{r}} = \int_C \left(y^2 + x^2 \frac{dy}{dx} \right) dx = \int_0^1 (x^4 + x^2 2x) dx = \frac{7}{10}.$$
 (1b)

 $\int_C \mathbf{F} \cdot d\mathbf{r}$ is clearly **PATH DEPENDENT** in general.

Example 2: Find $\int_C \underline{\mathbf{F}} \cdot d\underline{\mathbf{r}}$, where $\underline{\mathbf{F}} = (x - xy^2)\underline{\mathbf{i}} + (8y - x^2y)\underline{\mathbf{j}}$ and C is (a) the straight line y = x from (0,0) to (1,1) and (b) is the path firstly along y = 0 from (0,0) to (1,0), then along x = 1 from (1,0) to (1,1).

(a)
$$\Longrightarrow \int_C \mathbf{F} \cdot d\mathbf{r} = \int_C \left((x - xy^2) + (8y - x^2y) \frac{dy}{dx} \right) dx = \int_0^1 (9x - 2x^3) dx = 4.$$
 (2a)

(b)
$$\Longrightarrow \int_C \underline{\mathbf{F}} \cdot d\underline{\mathbf{r}} = \int_C ((x - xy^2) dx + (8y - x^2y) dy) = \int_0^1 x dx + \int_0^1 7y dy = 4.$$
 (2b)

In this case we obtain the **SAME** value for $\int_C \underline{\mathbf{F}} \cdot d\mathbf{r}$ along **DIFFERENT** paths.

Given a vector field $\underline{\mathbf{F}}(\underline{\mathbf{r}}) \equiv F_1(\underline{\mathbf{r}}) \underline{\mathbf{i}} + F_2(\underline{\mathbf{r}}) \underline{\mathbf{j}} + F_3(\underline{\mathbf{r}}) \underline{\mathbf{k}}$, suppose there exists a function $\phi(\underline{\mathbf{r}}) \equiv \phi(x, y, z)$ such that

$$\frac{\partial \phi}{\partial x} = F_1, \qquad \frac{\partial \phi}{\partial y} = F_2, \qquad \frac{\partial \phi}{\partial z} = F_3;$$
 (3a)

then

$$\int_{C_{\mathbf{A}\to\mathbf{B}}} \underline{\mathbf{F}} \cdot d\underline{\mathbf{r}} = \int_{C_{\mathbf{A}\to\mathbf{B}}} \left[\frac{\partial \phi}{\partial x} dx + \frac{\partial \phi}{\partial y} dy + \frac{\partial \phi}{\partial z} dz \right] = \int_{C_{\mathbf{A}\to\mathbf{B}}} d\phi = \phi(\mathbf{B}) - \phi(\mathbf{A}); \tag{3b}$$

that is, $\int_{C_{\mathbf{A} \to \mathbf{B}}} \underline{\mathbf{F}} \cdot d\underline{\mathbf{r}}$ depends only on the start point \mathbf{A} and the end point \mathbf{B} , and \mathbf{NOT} on the particular path C joining \mathbf{A} to \mathbf{B} .

If ϕ exists satisfying (3a), then

$$\frac{\partial F_1}{\partial y} = \frac{\partial}{\partial y} \left(\frac{\partial \phi}{\partial x} \right) = \frac{\partial}{\partial x} \left(\frac{\partial \phi}{\partial y} \right) = \frac{\partial F_2}{\partial x},
\frac{\partial F_1}{\partial z} = \frac{\partial}{\partial z} \left(\frac{\partial \phi}{\partial x} \right) = \frac{\partial}{\partial x} \left(\frac{\partial \phi}{\partial z} \right) = \frac{\partial F_3}{\partial x},
\frac{\partial F_2}{\partial z} = \frac{\partial}{\partial z} \left(\frac{\partial \phi}{\partial y} \right) = \frac{\partial}{\partial y} \left(\frac{\partial \phi}{\partial z} \right) = \frac{\partial F_3}{\partial y}.$$
(4)

One can show that if $\underline{\mathbf{F}}(\underline{\mathbf{r}}) \equiv F_1(\underline{\mathbf{r}}) \underline{\mathbf{i}} + F_2(\underline{\mathbf{r}}) \underline{\mathbf{j}} + F_3(\underline{\mathbf{r}}) \underline{\mathbf{k}}$ satisfies the 3 conditions in (4), i.e.

$$\frac{\partial F_1}{\partial y} = \frac{\partial F_2}{\partial x}, \qquad \frac{\partial F_1}{\partial z} = \frac{\partial F_3}{\partial x}, \qquad \frac{\partial F_2}{\partial z} = \frac{\partial F_3}{\partial y}; \tag{5}$$

then there exists ϕ satisfying (3a) and hence (3b) holds.

Such an \underline{F} is called **CONSERVATIVE** with the corresponding ϕ being the **POTENTIAL** of \underline{F} .

If C is a closed path and $\underline{\mathbf{F}}$ is conservative, then $\oint_C \underline{\mathbf{F}} \cdot d\underline{\mathbf{r}} = 0$ as $\mathbf{B} = \mathbf{A}$ in (3b).

Example 1:
$$\Longrightarrow \frac{\partial F_1}{\partial y} = 2y \neq 2x = \frac{\partial F_2}{\partial x} \Longrightarrow \underline{\mathbf{F}} \text{ is NOT conservative}$$

$$\Longrightarrow \int_C \underline{\mathbf{F}} \cdot d\underline{\mathbf{r}} \text{ is NOT path independent.}$$

Example 2:
$$\Rightarrow \frac{\partial F_1}{\partial y} = -2xy = \frac{\partial F_2}{\partial x}, \quad \frac{\partial F_1}{\partial z} = 0 = \frac{\partial F_3}{\partial x}, \quad \frac{\partial F_2}{\partial z} = 0 = \frac{\partial F_3}{\partial y}$$

$$\Rightarrow \quad \underline{\mathbf{F}} \text{ is conservative} \quad \Rightarrow \quad \int_C \underline{\mathbf{F}} \cdot d\underline{\mathbf{r}} \text{ is path independent.}$$

How to find the corresponding potential ϕ satisfying (3a), i.e.

(a)
$$\frac{\partial \phi}{\partial x} = x - xy^2$$
, (b) $\frac{\partial \phi}{\partial y} = 8y - x^2y$, (c) $\frac{\partial \phi}{\partial z} = 0$.
(a) $\implies \phi(x, y, z) = \frac{1}{2}x^2 - \frac{1}{2}x^2y^2 + f(y, z)$ (f an arbitrary function of y and z) $\implies \frac{\partial \phi}{\partial y} = -x^2y + \frac{\partial f}{\partial y}(y, z) = 8y - x^2y$ from (b) $\implies \frac{\partial f}{\partial y}(y, z) = 8y \implies f(y, z) = 4y^2 + g(z)$ (g an arbitrary function of z) $\implies \phi(x, y, z) = \frac{1}{2}x^2(1 - y^2) + 4y^2 + g(z) \implies \frac{\partial \phi}{\partial z} = \frac{dg}{dz}(z) = 0$ from (c) $\implies g(z) = \phi_0$ (ϕ_0 an arbitrary constant) $\implies \phi(x, y, z) = \frac{1}{2}x^2(1 - y^2) + 4y^2 + \phi_0$.

Hence in **Example 2:** $\int_C \underline{\mathbf{F}} \cdot d\underline{\mathbf{r}} = \phi(1,1,0) - \phi(0,0,0) = 4 \text{ as in (2a) and (2b)}.$

Example 3: Show that $\underline{\mathbf{F}} = 2xy\,\underline{\mathbf{i}} + (x^2 + 2y\sin z)\,\underline{\mathbf{j}} + y^2\cos z\,\underline{\mathbf{k}}$ is conservative and find the corresponding potential ϕ .

$$\frac{\partial F_1}{\partial y} \ = \ 2x \ = \ \frac{\partial F_2}{\partial x} \,, \quad \frac{\partial F_1}{\partial z} \ = \ 0 \ = \ \frac{\partial F_3}{\partial x} \,, \quad \frac{\partial F_2}{\partial z} \ = \ 2y \cos z \ = \ \frac{\partial F_3}{\partial y} \quad \Longrightarrow \quad \underline{\mathbf{F}} \ \text{ is conservative}.$$

$$\frac{\partial \phi}{\partial x} = F_1 = 2xy \implies \phi(x, y, z) = x^2y + f(y, z) \quad (f \text{ an arbitrary function of } y \text{ and } z)$$

$$\implies \frac{\partial \phi}{\partial y} = x^2 + \frac{\partial f}{\partial y}(y, z) = F_2 = x^2 + 2y \sin z \implies \frac{\partial f}{\partial y}(y, z) = 2y \sin z$$

$$\implies f(y, z) = y^2 \sin z + g(z) \quad (g \text{ an arbitrary function of } z)$$

$$\implies \phi(x, y, z) = x^2y + y^2 \sin z + g(z) \implies \frac{\partial \phi}{\partial z} = y^2 \cos z + \frac{dg}{dz}(z) = F_3 = y^2 \cos z$$

$$\implies g(z) = \phi_0 \quad \phi_0 \text{ an arbitrary constant}$$

$$\implies \phi(x, y, z) = x^2y + y^2 \sin z + \phi_0.$$