pfssoln9.tex

## SOLUTION 9 15.12.2015

Q1. We have to check the defining property (CE) (V.1, L18) for  $B = \emptyset$  and  $B = \Omega$ . For  $B = \emptyset$  both sides are zero; for  $B = \Omega$  both sides are EY. // (ii) We have to check (CE) for all sets  $B \in \mathcal{A}$ . The only integrand that integrates like Y over all sets is Y itself, or a function agreeing with Y except on a set of measure zero.

(iii) Recall that Y is always  $\mathcal{A}$ -measurable (this is the definition of Y being a random variable). For  $\mathcal{B} \subset \mathcal{A}$ , Y may not be  $\mathcal{B}$ -measurable, but if it is, the proof above applies with  $\mathcal{B}$  in place of  $\mathcal{A}$ .

(iv) (Tower property). If  $\mathcal{C} \subset \mathcal{B}$ ,  $E[E(Y|\mathcal{B}) |\mathcal{C}] = E[Y|\mathcal{C}]$  a.s.

*Proof.*  $E_{\mathcal{C}}E_{\mathcal{B}}Y$  is  $\mathcal{C}$ -measurable, and for  $C \in \mathcal{C} \subset \mathcal{B}$ ,

$$\int_{C} E_{\mathcal{C}}[E_{\mathcal{B}}Y]dP = \int_{C} E_{\mathcal{B}}YdP \quad (\text{definition of } E_{\mathcal{C}} \text{ as } C \in \mathcal{C})$$
$$= \int_{C} YdP \quad (\text{definition of } E_{\mathcal{B}} \text{ as } C \in \mathcal{B}).$$

So  $E_{\mathcal{C}}[E_{\mathcal{B}}Y]$  satisfies the defining relation for  $E_{\mathcal{C}}Y$ . Being also  $\mathcal{C}$ -measurable, it is  $E_{\mathcal{C}}Y$  (a.s.). //

9 (iv') (Tower property). If  $\mathcal{C} \subset \mathcal{B}$ ,  $E[E(Y|\mathcal{C}) |\mathcal{B}] = E[Y|\mathcal{C}]$  a.s.

*Proof.*  $E[Y|\mathcal{C}]$  is  $\mathcal{C}$ -measurable, so  $\mathcal{B}$ -measurable as  $\mathcal{C} \subset \mathcal{B}$ , so  $E[.|\mathcal{B}]$  has no effect, by (iii). //

Corollary.  $E[E(Y|\mathcal{C}) |\mathcal{C}] = E[Y|\mathcal{C}]$  a.s.

So the operation  $E[.|\mathcal{C}]$  is linear and *idempotent* (doing it twice is the same as doing it once), so is a *projection*. So we can use what we know about projections, from Ch. IV, Linear Algebra, Functional Analysis etc.

Q2. (i) For  $t \neq 0$ , X is Gaussian with zero mean (as B is), and continuous (again, as B is). The covariance of B is  $\min(s, t)$ . The covariance of X is

$$cov(X_s, X_t) = cov(sB(1/s), tB(1/t)) = E[sB(1/s).tB(1/t)] = st.E[B(1/s)B(1/t)]$$

 $= st.cov(B(1/s), B(1/t)) = st.\min(1/s, 1/t) = \min(t, s) = \min(s, t).$ 

This is the same covariance as Brownian motion. So, away from the origin, X is Brownian motion, as a Gaussian process is uniquely characterized by

its mean and covariance (from the properties of the multivariate normal distribution). So X is continuous. So we can define it at the origin by continuity. So X is Brownian motion everywhere -X is BM.

(ii) Since Brownian motion is 0 at the origin, X(0) = 0. Since Brownian motion is continuous at the origin,  $X(t) \to 0$  as  $t \to 0$ . This says that

$$tB(1/t) \to 0$$
  $(t \to 0)$ , i.e.  $B(t)/t \to 0$   $(t \to \infty)$ .

Note. For t integer, this is the Strong Law of Large Numbers applied to the distribution of B(1), which is standard normal. The above neat proof by *time-inversion* follows from the proof of existence of Brownian motion (defined to be continuous), given in lectures by the PWZ wavelet expansion.

Q3. Brownian bridge  $X_t := B_t - tB_1$  ( $t \in [0, 1]$ ) is Gaussian (it is obtained from the Gaussian process B by linear operations – as in the multivariate normal distribution, IV.3). It has mean 0 (as B does), and covariance

$$E[X_s X_t] = E[(B_s - sB_1)(B_t - tB_1)] = E[B_s B_t] - tE[B_s B_1] - sE[B_t B_1] + stE[B_1^2]$$
  
= min(s,t)-tmin(s,1)-smin(t,1)+st = min(s,t)-st-st+st = min(s,t)-st.  
NHB