

**SMF EXAMINATION SOLUTIONS 2014-15**

Q1. (i) (a) The log-likelihood is

$$\ell = -n \log 2 - \sum |x_i - \theta|.$$

To maximise this – i.e. minimise  $\sum |x_i - \theta|$  – draw a graph. From this, the sum is minimised by  $\theta = Med$ , and increases linearly (slope +1 to the right, –1 to the left) on either side. So the MLE is  $\hat{\mu} = Med$ . [3]

(b) With one reading, as above,  $\ell$  decreases with slope -1 to the right of  $Med$ , slope +1 to the left of  $Med$ . So  $(\ell')^2 = 1$  (except at  $\lambda = Med$ , where the derivative is not defined – but we are going to integrate, and so can neglect null sets, e.g single points). So  $I = \int (\partial \log f / \partial \theta)^2 f = \int f = 1$ , as  $f$  is a density. So the CR bound is  $1/n$ . [3]

(c) We are given that  $Med$  is asymptotically normal, and that its mean is  $med = \theta$ , so  $Med$  is asymptotically unbiased. By symmetry, the population median is  $med = \theta$ , where the density is  $\frac{1}{2}$ . So  $4f(med)^2 = 1$ , and the asymptotic variance of the sample median is  $1/n$ , the CR bound, so  $Med$  is also asymptotically efficient. [4]

(ii) (a)

$$f(x; \mu) = \frac{1}{\pi(1 + (x - \mu)^2)}, \quad \ell = \log f = c - \log[1 + (x - \mu)^2],$$

$$\ell' = \frac{2(x - \mu)}{1 + (x - \mu)^2}, \quad \ell'(\mathbf{x}; \theta) = 2 \sum_1^n \frac{(x_i - \mu)}{1 + (x_i - \mu)^2}.$$

But we have efficiency iff  $\ell'$  factorises in the form  $\ell'(\mathbf{x}; \theta) = A(\theta)(u(\mathbf{x}) - \theta)$ . The likelihood here does not factorise, so there is no efficient estimator. [4]

(b) The information per reading is

$$E[(\ell')^2] = \int (\partial f / \partial \mu)^2 f = \frac{4}{\pi} \int \frac{(x - \mu)^2}{[1 + (x - \mu)^2]^3} dx = \frac{4}{\pi} \int \frac{x^2}{[1 + x^2]^3} dx = \frac{4}{\pi} I,$$

say. Given  $I = \pi/8$  (to evaluate  $I$  by Complex Analysis: use  $f(z) := z^2/[1 + z^2]^3$ , the contour  $\Gamma$  a large semicircle in the upper half-plane;  $f$  has a triple pole inside  $\Gamma$  of residue  $-i/16$ , so  $I = 2\pi i Res = \pi/8$ ), so the information per reading is  $\frac{1}{2}$ . So the information in a sample of size  $n$  is  $n/2$ , and the MLE has asymptotic variance  $2/n$ . As in (i),  $med = \mu$ ,  $f(med) = 1/\pi$ , so the sample median  $Med$  has asymptotic variance  $1/(4nf(med)^2) = \pi^2/4n$ . So the asymptotic efficiency is their ratio,  $8/\pi^2 \sim 81\%$ . [6]

[Seen – Problems]

Q2.  $y_A = a + \epsilon_1$ ,  $y_B = b + \epsilon_2$ ,  $y_{B-A} = -a + b + \epsilon_3$ . So the regression model is  $y = A\beta + \epsilon$ , where  $y$  is the 3-vector of readings,  $\epsilon$  is the 3-vector of errors,  $\beta := (a, b)^T$  is the 2-vector of parameters and  $A$  is the design matrix.

(a)

$$A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ -1 & 1 \end{pmatrix}. \quad [3]$$

(b)

$$C := A^T A = \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ -1 & 1 \end{pmatrix} = \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix}; \quad |C| = 3;$$

$$C^{-1} = \frac{1}{3} \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix}, \quad C^{-1} A^T = \frac{1}{3} \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \end{pmatrix} = \frac{1}{3} \begin{pmatrix} 2 & 1 & -1 \\ 1 & 2 & 1 \end{pmatrix}. \quad [3]$$

(c)

$$P = \frac{1}{3} \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} 2 & 1 & -1 \\ 1 & 2 & 1 \end{pmatrix} = \frac{1}{3} \begin{pmatrix} 2 & 1 & -1 \\ 1 & 2 & 1 \\ -1 & 1 & 2 \end{pmatrix}, \quad I - P = \frac{1}{3} \begin{pmatrix} 1 & -1 & 1 \\ -1 & 1 & -1 \\ 1 & -1 & 1 \end{pmatrix}. \quad [4]$$

(d) The parameter estimates are

$$C^{-1} A^T y = \frac{1}{3} \begin{pmatrix} 2 & 1 & -1 \\ 1 & 2 & 1 \end{pmatrix} \begin{pmatrix} y_A \\ y_B \\ y_{B-A} \end{pmatrix} = \begin{pmatrix} \hat{a} \\ \hat{b} \end{pmatrix} :$$

$$\hat{a} = (2y_A + y_B - y_{B-A})/3, \quad \hat{b} = (y_A + 2y_B + y_{B-A})/3. \quad [3]$$

(e) The fitted values are  $\hat{y} = Py$ , which can be written in two ways:

$$\begin{pmatrix} (2y_A + y_B - y_{B-A})/3 \\ (y_A + 2y_B + y_{B-A})/3 \\ (-y_A + y_B + 2y_{B-A})/3 \end{pmatrix} = \begin{pmatrix} \hat{a} \\ \hat{b} \\ \hat{b} - \hat{a} \end{pmatrix}. \quad [3]$$

(f) As  $n = 3$ ,  $p = 2$  here, the ranks of  $P$ ,  $I - P$  are 2 and 1. [2]

(g) Write  $SSE$ , the *sum of squares for error*, for  $y^T(I - P)y$ . As  $n - p = 1$ ,  $\hat{\sigma}^2 = SSE/(n - p) = y^T(I - P)y$ , which can be calculated by above. With numerical data,  $SSE$  is the sum of squared residuals,  $\sum(y_i - \hat{y}_i)^2$ . [2]

[Unseen; similar seen in lectures and problems]

Q3.  $x_2|x_1 \sim N(\mu_2 + \Sigma_{21}\Sigma_{11}^{-1}(x_1 - \mu_1), \Sigma_{22} - \Sigma_{21}\Sigma_{11}^{-1}\Sigma_{12})$ .

If  $x_1, x_2, x_3 \sim N(\mu, \Sigma)$  are independent,  $y_1 := x_1 + x_2$ ,  $y_2 := x_2 + x_3$ , then  $y = Ax$ , where

$$y = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}, \quad x = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}, \quad A = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \end{pmatrix}.$$

So the mean is

$$Ey = A.Ex = A\mu = \begin{pmatrix} \mu_1 + \mu_2 \\ \mu_2 + \mu_3 \end{pmatrix} = m, \quad [3]$$

say. The variance is

$$\begin{aligned} \text{var}(y) &= A\Sigma A^T = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & \rho & \rho \\ \rho & 1 & \rho \\ \rho & \rho & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 1 & 1 \\ 0 & 1 \end{pmatrix} \\ &= \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} 1+\rho & 2\rho \\ 1+\rho & 1+\rho \\ 2\rho & 1+\rho \end{pmatrix} = \begin{pmatrix} 2+2\rho & 1+3\rho \\ 1+3\rho & 2+2\rho \end{pmatrix}. \quad [5] \end{aligned}$$

So

$$y \sim N(m, \Sigma_y), \quad m = \begin{pmatrix} \mu_1 + \mu_2 \\ \mu_2 + \mu_3 \end{pmatrix}, \quad \Sigma_y = \begin{pmatrix} 2+2\rho & 1+3\rho \\ 1+3\rho & 2+2\rho \end{pmatrix}. \quad [4]$$

(ii) So on conditioning, the four partitioned submatrices are the four components; the conditional mean and conditional variance of  $y_1|y_2$  are

$$m_1 + \frac{1+3\rho}{2(1+\rho)}(y_2 - m_2) = \mu_1 + \mu_2 + \frac{1+3\rho}{2(1+\rho)}(y_2 - \mu_2 - \mu_3), \quad 2(1+\rho) - \frac{(1+3\rho)^2}{2(1+\rho)}. \quad [4]$$

So

$$y_1|y_2 \sim N\left(\mu_1 + \mu_2 + \frac{1+3\rho}{2(1+\rho)}(y_2 - \mu_2 - \mu_3), 2(1+\rho) - \frac{(1+3\rho)^2}{2(1+\rho)}\right). \quad [4]$$

[Unseen; similar seen – lectures and problems]

- Q4. *ARMA*(1, 1).  $X_t = \phi X_{t-1} + \epsilon_t + \theta \epsilon_{t-1}$ :  $(1 - \phi B)X_t = (1 + \theta B)\epsilon_t$ .  
 (i) Condition for stationarity and invertibility:  $|\phi| < 1$ ;  $|\theta| < 1$ . [2, 2]  
 (ii) Assuming these:

$$\begin{aligned} X_t &= (1 - \phi B)^{-1}(1 + \theta B)\epsilon_t = (1 + \theta B)\left(\sum_0^\infty \phi^i B^i\right)\epsilon_t \\ &= \epsilon_t + \sum_1^\infty \phi^i B^i \epsilon_t + \theta \sum_0^\infty \phi^i B^{i+1} \epsilon_t = \epsilon_t + (\phi + \theta) \sum_1^\infty \phi^{i-1} B^i \epsilon_t : \\ X_t &= \epsilon_t + (\phi + \theta) \sum_{i=1}^\infty \phi^{i-1} \epsilon_{t-i}. \end{aligned}$$

- (a) *Variance*: lag  $\tau = 0$ . The  $\epsilon$ s are uncorrelated with variance  $\sigma^2$ , so

$$\begin{aligned} \gamma_0 &= \text{var} X_t = E[X_t^2] = \sigma^2 + (\phi + \theta)^2 \sum_1^\infty \phi^{2(i-1)} \sigma^2 \\ &= \sigma^2 + \frac{(\phi + \theta)^2 \sigma^2}{(1 - \phi^2)} = \sigma^2(1 - \phi^2 + \phi^2 + 2\phi\theta + \theta^2)/(1 - \phi^2) : \\ \gamma_0 &= \sigma^2(1 + (\phi + \theta)^2/(1 - \phi^2)) = \sigma^2(1 + 2\phi\theta + \theta^2)/(1 - \phi^2) \quad [8] \end{aligned}$$

- (b) *Covariance*: lag  $\tau \geq 1$ .

$$X_{t-\tau} = \epsilon_{t-\tau} + (\phi + \theta) \sum_{j=1}^\infty \phi^{j-1} \epsilon_{t-\tau-j}.$$

Multiply the series for  $X_t$  and  $X_{t-\tau}$  and take expectations:

$$\begin{aligned} \gamma_\tau &= \text{cov}(X_t, X_{t-\tau}) = E[X_t X_{t-\tau}], \\ &= E\left[\left[\epsilon_t + (\phi + \theta) \sum_{i=1}^\infty \phi^{i-1} \epsilon_{t-i}\right] \cdot \left[\epsilon_{t-\tau} + (\phi + \theta) \sum_{j=1}^\infty \phi^{j-1} \epsilon_{t-\tau-j}\right]\right]. \end{aligned}$$

The  $\epsilon_t$ -term in the first  $[\cdot]$  gives no contribution. The  $i$ -term in the first  $[\cdot]$  for  $i = \tau$  and the  $\epsilon_{t-\tau}$  in the second  $[\cdot]$  give  $(\phi + \theta)\phi^{\tau-1}\sigma^2$ . The product of the  $i$  term in the first sum and the  $j$  term in the second contributes for  $i = \tau + j$ ; for  $j \geq 1$  it gives  $(\phi + \theta)^2 \phi^{\tau+j-1} \cdot \phi^{j-1} \cdot \sigma^2$ . So

$$\gamma_\tau = (\phi + \theta)\phi^{\tau-1}\sigma^2 + (\phi + \theta)^2 \phi^\tau \sigma^2 \sum_{j=1}^\infty \phi^{2(j-1)}.$$

The geometric series is  $1/(1 - \phi^2)$  as before, so

$$\gamma_\tau = \sigma^2(\phi + \theta)\phi^{\tau-1} + \sigma^2 \phi^\tau (\phi + \theta)^2 / (1 - \phi^2) \quad (\tau \geq 1).$$

This decreases geometrically beyond the first term  $\gamma_0 = 1$ , and this behaviour is indicative of *ARMA*(1, 1). [8]

[Seen – lectures and problems]

Q5. (i) Markowitz' work of 1952 (which led on to CAPM in the 1960s) gave two key insights:

(a). *Think of risk and return together, not separately.* Now return corresponds to mean (= mean rate of return), risk corresponds to variance – hence *mean-variance* analysis, *efficient frontier*, etc. – maximise return for a given level of risk/minimise risk for a given return rate). [2]

(b). *Diversify* (don't 'put all your eggs in one basket'). Hold a *balanced portfolio* – a range of risky assets, with lots of *negative correlation* – so that when things change, losses on some assets will be offset by gains on others. [2]

Hence the vector-matrix parameter  $(\mu, \Sigma)$  is accepted as an essential part of any model in mathematical finance.

(ii) *Elliptical distributions.*

The normal density in higher dimensions is a multiple of  $\exp\{-\frac{1}{2}(x - \mu)^T \Sigma^{-1}(x - \mu)\}$ , where the matrices  $\Sigma, \Sigma^{-1}$  are *positive definite* (PD), so the contours  $(x - \mu)^T \Sigma^{-1}(x - \mu) = \text{const.}$  are *ellipsoids*. The general *elliptically contoured* distribution has a density

$$f(x) = \text{const.}g((x - \mu)^T \Sigma^{-1}(x - \mu)).$$

This is a *semi-parametric* model, where  $\theta := (\mu, \sigma)$  is the parametric part and the *density generator*  $g$  is the non-parametric part. [4]

(iii) *Normal (Gaussian) model:* elliptically contoured ( $g(\cdot) = e^{-\frac{1}{2}\cdot}$ ). Though very useful, it has various deficiencies, e.g.:

(a) It is *symmetric*. Many financial data sets show asymmetry, or *skew*. This reflects the asymmetry between profit and loss. Big profits are nice; big losses can be lethal (to the firm – bankruptcy). [3]

(b) It has extremely thin tails. Most financial data sets have tails that are *much fatter* than the ultra-thin normal tails. [3]

(iv) For asset returns (= profit/loss over initial asset price) over a period, the *return period:* matters vary dramatically with the return period.

(a) For *long* return periods (monthly, say – the Rule of Thumb is that 16 trading days suffice), the CLT applies, and asset returns are approximately *normal* ('aggregational Gaussianity'). [2]

(ib) For *intermediate* return periods (daily, say), a commonly used model is the *generalised hyperbolic (GH)* – log-density a hyperbola, with linear asymptotes, so density decays like the exponential of a linear function). [2]

(c) For *high-frequency* returns ('tick data', say – every few seconds), the density typically decays like a power (as with the Student  $t$  distribution). [2]

[Seen – lectures.]

Q6. (i) Edgeworth's theorem says that if  $x \sim N(\mu, \Sigma)$  and  $K := \Sigma^{-1}$ ,

$$f(x) \propto \exp\left\{-\frac{1}{2}(x - \mu)^T K (x - \mu)\right\}. \quad [1]$$

$$f(x_1, x_2) \propto \exp\left\{-\frac{1}{2}(x_1^T - \mu_1^T, x_2^T - \mu_2^T) \begin{pmatrix} K_{11} & K_{12} \\ K_{21} & K_{22} \end{pmatrix} \begin{pmatrix} x_1 - \mu_1 \\ x_2 - \mu_2 \end{pmatrix}\right\},$$

giving (as a scalar is its own transpose, so the two cross-terms are the same)

$$\exp\left\{-\frac{1}{2}[(x_1^T - \mu_1^T)K_{11}(x_1 - \mu_1) + 2(x_1^T - \mu_1^T)K_{12}(x_2 - \mu_2) + (x_2^T - \mu_2^T)K_{22}(x_2 - \mu_2)]\right\}.$$

So

$$\begin{aligned} f_{1|2}(x_1|x_2) &= f(x_1, x_2)/f_2(x_2) \\ &\propto \exp\left\{-\frac{1}{2}[(x_1^T - \mu_1^T)K_{11}(x_1 - \mu_1) + 2(x_1^T - \mu_1^T)K_{12}(x_2 - \mu_2)]\right\}, \quad (*) \end{aligned}$$

treating  $x_2$  here as a constant and  $x_1$  as the argument of  $f_{1|2}$ . [4]

By Edgeworth's theorem again, if the conditional mean of  $x_1|x_2$  is  $\nu_1$ ,

$$f_{1|2}(x_1|x_2) \propto \exp\left\{-\frac{1}{2}(x_1^T - \nu_1^T)V_{11}(x_1 - \nu_1)\right\}, \quad (**)$$

for some matrix  $V_{11}$ . So  $x_1|x_2$  is multinormal (as may be quoted). [3]

Equating coefficients of the quadratic term gives the conditional concentration matrix of  $x_1|x_2$  as  $V_{11} = K_{11}$ :

$$\text{conc}(x_1|x_2) = K_{11}. \quad [3]$$

So the conditional covariance matrix is  $K_{11}^{-1}$ . Then equating linear terms in (\*) and (\*\*) gives the conditional mean:

$$x_1^T K_{11} \nu_1 = x_1^T K_{11} \mu_1 - x_1^T K_{12} (x_2 - \mu_2) : \quad \nu_1 := E[x_1|x_2] = \mu_1 - K_{11}^{-1} K_{12} (x_2 - \mu_2). \quad [3]$$

So

$$x_1|x_2 \sim N(\mu_1 - K_{11}^{-1} K_{12} (x_2 - \mu_2), K_{11}^{-1}). \quad [2]$$

Using the quoted result for the inverse of a partitioned matrix gives

$$\begin{aligned} M &= K_{11}, & M^{-1} &= K_{11}^{-1} = \Sigma_{11} - \Sigma_{12} \Sigma_{22}^{-1} \Sigma_{21}, \\ K_{11}^{-1} K_{12} &= M^{-1} (-M B D^{-1}) = -B D^{-1} = -\Sigma_{12} \Sigma_{22}^{-1}. \end{aligned}$$

Combining,

$$x_1|x_2 \sim N(\mu_1 + \Sigma_{12} \Sigma_{22}^{-1} (x_2 - \mu_2), \Sigma_{11} - \Sigma_{12} \Sigma_{22}^{-1} \Sigma_{21}). \quad [4]$$

[Seen - Problems]

NHB